Previous lecture review

- to parallelize execution each device is connected to a controller; all controllers are joined by common bus; communication between controllers and CPU is interrupt based
- the storage is hierarchical fastest types of storage are accessed first; to exploit locality of reference caching mechanism is used; faster types of storage tend to be more expensive and less reliable
- protection needs to be used in multiprogramming and timesharing OSes:
- I/O protection
- memory protection
- CPU protection

Lecture 3: OS objectives and organization

- OS objectives
 - process management
 - memory management
 - disk/file management
 - networking, command interpreting
- system calls OS interface to application programs
- OS design approaches:
 - monolithic kernel
 - layering
 - microkernel
 - virtual machine

Process management

- OS manages many kinds of activities:
 - user programs

etc.

- system programs: printer spoolers, name servers, file servers,
- a running program is called a process
 - a process includes the complete execution context (code, data, PC, registers, OS resources in use, etc.)
 - a process is not a program
 - program a sequence of instructions (passive)
 - process one instance of a program in execution (acitve);
 - many processes can be running the same program and one
 - program may cause to create multiple processes
- from OS viewpoint process is a unit of work; OS must:
 - create, delete, suspend, resume, and schedule processes
 - support inter-process communication and synchronization, handle deadlocks

Disk management

- The size of the disk is much greater than main memory and, unlike main memory, disk is persistent (endures system failures and power outages)
- OS hides peculiarities of disk usage by managing disk space at low level:
 - keeps track of used spaces
 - · keeps track of unused (free) space
 - keeps track of "bad blocks"
- OS handles low-level disk functions, such as:
 - schedules of disk operations
 - and head movement

Memory management

- primary (main) memory (RAM)
 - provides direct access storage for CPU
 - processes must be in main memory to execute
- OS must:
 - mechanics
 - keep track of memory in use
 - keep track of unused ("free") memory
 - protect memory space
 - allocate, deallocate space for processes
 - swap processes: memory <-> disk
 - policies
 - decide when to load each process into memory
 - decide how much memory space to allocate to each
 - process
 - · decide when a process should be removed from memory

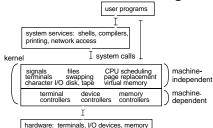
File management

- disks provide long-term storage, but are awkward to use directly
- file a logical named persistent collection of data maintained by OS
- file system a logical structure that that is maintained by OS to simplify file manipulation; usually directory based
- OS must:
 - create and delete files and directories
 - manipulate files and directories read, write, extend, rename, copy, protect
 - provide general higher-level services backups, accounting, quotas
- note the difference between disk management and file system management

System calls

- system calls provide the interface between a process and the . operating system.
- It is a way of transferring control to the OS so that it can carry out a certain function for the process.
- Example: a program that opens a text file and prints on the screen uses the following system calls:
 - open a file if the file could not be opened inform the program
 - + read a line of file
 - print the line just read on the screen
 - continue the last two system calls until the end of the file is reached
- close file

Monolithic kernel OS design



- advantages: speed and ease of operation (everything is at hand)

disadvantages:

- hard to develop, maintain, modify and debug
- kernel gets bigger as the OS develops

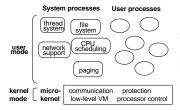
the kernel is the protected part of the OS that runs in monitor mode

critical OS data structures and device registers are protected from user programs can use privileged instructions

Layered Design

- divide OS into layers
- each layer uses services provided by next lower layer yet the implementation of these services are hidden from the upper laver
- THE Operating system layer structure:
- - user programs
 buffering for input and output devices
- operator-console device driver
- memory management
 CPU scheduling
- hardware
- advantages: easier development and implementation
- · disadvantages: not always easy to break down on layers, slower (each level adds overhead)
 - ex: CPU scheduler is lower than virtual memory driver (driver may need to wait for I/O) yet the scheduler may have more info than can fit in memory
- examples: THE, OS/2

Microkernel



 small kernel implements communication (usually messages) when system services are required microkernell calls other parts of OS running in user modes and passes the request there

- advantages: reliability, ease of development, modularity parts can be . replaced and tailored to the architecture, user requirements etc.
- disadvantages: slow
- examples: Mach(US), MacOS X, Windows NT

Virtual Machine

- system calls can be considered an
- enhancement of hardware's instruction set
- extend further virtual machine
- each user task is provided with an abstract (virtual machine) which OS + hardware implement
- IBM pioneered
- Java VM modern example
- JVM
 - Java source code is translated into an architecture independent iava bytecode
 - bytecode is executed by JVM
 - JVM can be implemented purely in software or in hardware
 - JVM verifies bytecode's correctness and then either interprets ٠
 - (tranlates the code into machines instructions one by one)
 - or just-in-time (JIT) comples to optimize
- adv. portability at binary-level, security, greater language flexibility

dis. - speed(?)